

SELF-PROPELLED SCISSOR LIFTS

Background

Self-propelled scissor lifts, the most common type of Mobile Elevating Work Platforms (MEWPs), move vertically through folding supports in an 'X' pattern, known as a scissor mechanism. They are classified in 2 main categories based on how they are powered and where they are used. 1.Battery-powered (or electric) scissor lifts are used mainly indoors on slab surfaces, while 2. Engine-powered lifts are used outdoors where the surfaces are frequently uneven (for this reason they are commonly referred to be for 'rough terrain'). Regardless of how they are powered, they include many sensors and controls to manage movement, safety, and mainly stability (operators on the platform are subject to fall hazards, therefore safety is a priority).

"All functions
and movements
are controlled using
Sensata's platform control
systems and sensors to
guarantee compliance with
international safety
standards"

Solution

Operator Controls:

For decades, Sensata has been a marketleading supplier of complete platform control systems for scissor lifts, either battery or engine powered. The platform control unit and the electronic control unit (or ground control unit for the engine powered) can connect and control a variety of digital and analog machine interface as joysticks, sensors, limit switches, motor controllers, pushbuttons, and alarms controlled through a dedicated CAN-bus system.

The new K610 generation of scissor lift controllers integrate an open source platform, CoDeSys, which enables manufacturers to create their own customized functionality.

Motor Controls:

The M701 is a highly efficient DC pump motor controller designed for industrial vehicle platforms. With IP67 ingress protection, advanced MOSFET drive technology, and short circuit protection, it allows for a high degree of safety and reliability.

Sensors:

Sensata can also supply a complete set of main sensors: the high-pressure sensor (PTE series) that controls the hydraulic pressure of the main cylinder, the angle sensor (9360 Series) used to determine the height of the platform, and the inclinometer (T series or other) to control the chassis inclination for safety reasons. The pressure and angle sensor used in combination are also aimed to control the platform overload condition, which is required to comply with ANSI 92 and EN280 safety standards.



Rough Terrain (engine-powered) scissor lift



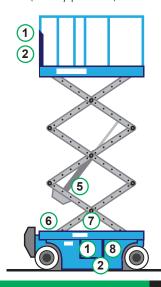
Slab (battery-powered) scissor lift

RELATED PRODUCTS

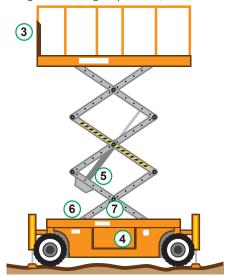
Reference on Diagram	Product		Features	Function
1		P610 E610	 3 Analog Inputs integrated IP65 USB 2 CAN, 2 USB 40 input/output Multi-language, Large LCD display 	Lift Control System
2		K330	 Entry-level lift control solution 7 segment display 1 CAN, 1 UART Reliable lifetime performance 	Lift Control System
3		PCU100	Extensive integrated controlsIP65	Platform Control Unit
4	8:0	ECU120	• CAN, MCU • 70 input/output	Ground Control Unit
5	8	PTE7500	 High pressure MSG (Micro Silicon Strain Gauge) CANopen output; Easy integration into ECU 	Pressure Sensor
6		9360 Series	Hall effect sensor IP67	Angle Sensor
7		T Series	 High resolution 0.01° High accuracy 0.1° 	Inclinometer
8	0	M701	 Highly efficient motor controller Advanced MOSFET drive technology and short-circuit protection IP67 ingress protection 	DC Motor Controller

GENERAL DIAGRAM

Slab (battery-powered) scissor lift



Rough Terrain (engine-powered) scissor lift



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