

FHK5

PROFIBUS ABSOLUTE SINGLE-TURN ENCODER



Features

- FHK515, standard encoder Ø58mm with Profibus interface
- Robust and compact conception
- Blind shaft \emptyset 15mm reduction hub available
- Precision ball bearings with sealing joint
- High temperatures performances -40°C ... +85°C
- Code disc made of unbreakable and durable plastic
- Resolution: 13 bits = 8192 steps/turn (max 16 bits)
- Polarity inversion and short circuit protection
- Highly integrated circuit in SMD-technology



Mechanical

	Cover : aluminum	
Material (option stainless steel)	Body: aluminum	
(option stanness steel)	Shaft: stainless steel	
Max. shaft loading	Axial: 40 N	
	Radial: 110 N	
Shaft inertia	≤ 30 g.cm ²	
Torque	≤3 N.cm	
Speed (continuous)	6 000 RPM	
Shock (EN60068-2-27)	≤ 100 g (half sine, 6 ms)	
Perm. shocks(EN 60028-2-29)	≤ 10 g (half sine, 16ms)	
Vibration (EN60068-2-6)	≤ 10 g (10Hz 1 000Hz)	
Weight (Aluminium Version)	600 g	
Operating temperature	- 40 + 85 °C (encoder T°)	
Storage temperature	- 40 + 85 °C	
Humidity	98 % without condensation	



Electrical

Interface	ISO 11898
Transmission rate	Max 12 MBauds
Device addressing	by rotary switches
Power supply	10 - 30Vdc
Current consumption	max 100mA (24Vdc)
Power consumption	max 2,5W
Step Frequency LSB	800 kHz
Accuracy	+ ½ LSB
EMC	EN 61000-6-4 EN 61000-6-2



PROGRAMMABLE PARAMETERS

The Profibus-DP interface supports CLASS 1 and CLASS 2 functionality according to the encoder profile. In addition to these functions the GSD-file supports further features, for example software limit switches. Further more, the following encoder parameters can be programmed directly via the

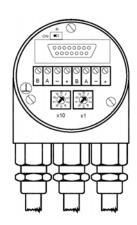
Counting Direction	This parameter counting direction defines whether the output code increases or decreases when the shaft rotates clockwise.	
Resolution (positions per turns)	The parameter 'resolution per revolution' is used to program the desired number of steps per revolution. Each value between 1 and the physical resolution per revolution can be programmed	
Reset (RAX)	The preset value is the desired position value, which should be reached at a certain physical position of the axis. The position value is set to the desired process value by the parameter preset	
Velocity	The implemented software can additionally deliver the current velocity. This value is transmitted in binary code, 16 Bit, in addition to the process value It is possible to choose between four different units: steps per 10 ms, per 100 ms, per 1000 ms and revolutions per minute	
Software limit switches function	Two software limit switches can be set. If the position value falls below the lower or exceeds the higher limit switch, a status bit in the process value is set	



The rotary encoder is connected by two or three cables, depending on whether the power supply is integrated into the bus cable or connected separately. If the power supply is integrated into the bus cable one of the cable glands can be fitted with a plug. The cable glands are suitable for cable diameters from 6.5 up to 9 mm

The Profibus-DP device address is set by user-friendly rotary switches in the connection cap. Allowed addresses are between 1 and 99, each can only be used once. The connection cap can easily be opened for installation by removing the two cap screws

Termination resistors are integrated in the connection cap. These must be switched on if the encoder is connected









All dimensions are in: inches [millimeters]

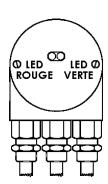
FHK515-PR0F (connection cap included) 71 23 Max. W**=30 Min. W**=15 ** hollow shaft depth ** hollow shaft depth ** wrench size =17

Allowed shaft movements	axial	radial
static	± 0.3 mm	± 0.5 mm

Shaft diameter can be reduced at 12mm, 10mm or 8mm by reduction ring (by inserting them into the hollow shaft)

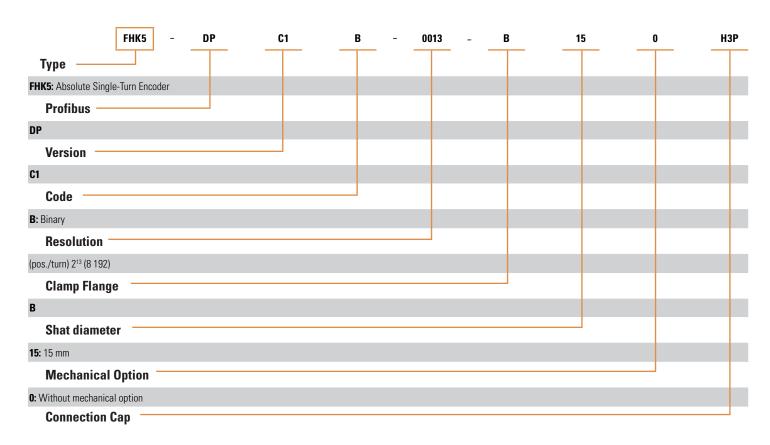
Red LED	Green LED	Status/possible cause	
Dark	Dark	No power supply	
Bright	Bright	Encoder is ready for operation but it has not received any configuration data after power on. Possible causes: address setting incorrect, Bus lines not connected correctly	
Bright	Parameter or configuration error. The encoder receives configuration or parameter daincorrect length or inconsistent data Possible cause: parameter value "total measuring range" too high		
Flashing	Bright	The encoder is ready for operation but not addressed by the master (e.g. incorrect address in configuration).	
Bright	Dark	Encoder has not received any data for a longer period (about 40 sec.) Possible cause: bus line has been interrupted	
Dark	Bright	Normal operation in data exchange mode	

Led status at the front



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AGENCYAPPROVALS&CERTIFICATIONS





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