MXM5 PROFIBUS ABSOLUTE MULTI-TURN ENCODER



Features

- MXM5, standard encoder Ø58mm with Profibus interface
- Robust and compact conception
- Solid shaft version Ø 10 mm (06 mm available upon request)

Sensata

Technologies

- Precision ball bearings with sealing flange
- High temperatures performances -40°C ... +85°C
- Code disc made of unbreakable and durable plastic
- Mechanical memorisation of the number of turns by gears
- Resolution: 13 bits = 8192 steps/turn
- Number of Turns: 12 bits = 4096 turns
- Polarity inversion and short circuit protection
- Highly integrated circuit in SMD-technology



Mechanical

Material	Cover: Stainless Steel Body: Stainless Steel Shaft: Stainless Steel					
Max. Shaft Loading	Axial: 40 N Radial: 110 N					
Shaft Inertia	\leq 30 g.cm ²					
Torque	\leq 3 N.cm					
RPM (Continuous Operation)	6 000 rpm					
Shock (EN 60068-2-27)	\leq 100 g (half-sinus, 6 ms)					
Shock (EN 60028-2-29)	\leq 10 g (half-sinus, 16ms)					
Vibrations (EN 60068-2-6)	\leq 10 g (10Hz 1 000Hz)					
Weight	800 g					
Operating Temperature	- 40 + 85 °C					
Storage Temperature	- 40 + 85 °C					
Humidity	98% without Condensation					
Protection class (EN 60529)	IP67					

Lifetime in 10 ⁸ Revolutions with F_a / F_r (Axial / Radial)							
40 N / 60 N	40 N / 80 N	40 N / 110 N					
25	10	4					





Interface	SO 11898							
Transmission Rate	x 12 MBauds							
Device Addressing	Rotary Switches							
Power Supply	- 30Vdc							
Current Consumption	ax 100mA (24Vdc)							
Power Consumption	lax 2,5W							
Step Frequency LSB	800 kHz							
Accuracy	+ ½ LSB							
EMC	EN 61000-6-4 EN 61000-6-2							
Electrical Lifetime	> 10 ⁵ h							



PROGRAMMABLE PARAMETERS

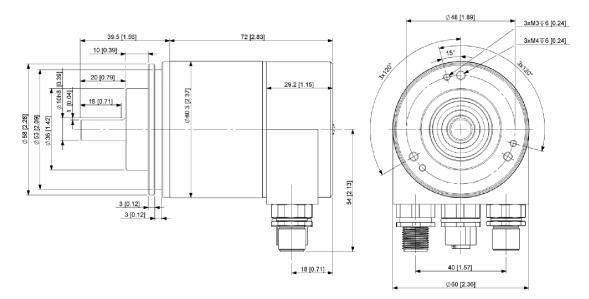
The Profibus-DP interface supports CLASS 1 and CLASS 2 functionality according to the encoder profile. In addition to these functions the GSD-file supports further features, for example software limit switches. Further more, the following encoder parameters can be programmed directly via the Profibus-DP network without any extra device.

Counting Direction	This parameter counting direction defines whether the output code increases or decreases when the shaft rotates clockwise					
Resolution (Positions per Turns)	The parameter 'resolution per revolution' is used to program the desired number of steps per revolution. Each value between 1 and the physical resolution per revolution can be programmed					
Total Resolution "Max-RANGE"	This parameter is used to program the desired number of measuring units over the total measuring range. This value may not exceed the total physical resolution of the absolute rotary encoder					
Reset (RAX)	The preset value is the desired position value, which should be reached at a certain physical position of the axis. The position value is set to the desired process value by the parameter preset					
Velocity	The implemented software can additionally deliver the current velocity. This value is transmitted in binary code, 16 Bit, in addition to the process value. It is possible to choose between four different units: steps per 10 ms, per 100 ms, per 1000 ms and revolutions per minute					
Software Limit Switches Function	Two software limit switches can be set. If the position value falls below the lower or exceeds the higher limit switch, a status bit in the process value is set					
Teach-In (Online Parameterization)	A special mode is available for commissioning phase of the device. This makes it possible to change parameters while the encoder is in data exchange mode					

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MXM510-PROFS (Connection Cap Included)

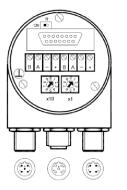


Red LED	Green LED	Status / possible cause
Dark	Dark	No power supply
Bright	Bright	Encoder is ready for operation but it has not received any configuration data after power on. Possible causes: address setting incorrect, Bus lines not connected correctly
Bright	Flashing	Parameter or configuration error. The encoder receives configuration or parameter data with incorrect length or inconsistent data. Possible cause: parameter value "total measuring range" too high
Flashing	Bright	The encoder is ready for operation but not addressed by the master (e.g. incorrect address in configuration)
Bright	Dark	Encoder has not received any data for a longer period (about 40 sec.) Possible cause: bus line has been interrupted
Dark	Bright	Normal operation in data exchange mode
Dark	Flashing	Commissioning mode

Interface

The Profibus-DP device address is set by user-friendly rotary switches in the connection cap. Allowed addresses are between 1 and 99, each can only be used once. The connection cap can easily be opened for installation by removing the two cap screws. Termination resistors are integrated in the connection cap. These must be switched on if the encoder is connected at the end or the beginning of the bus.

Connection



Connector 5 Pins (Left)

Pin	Description							
1	Not Connected							
2	Line Bus A (Bus in)							
3	Not Connected							
4	Line Bus B (Bus in)							
5	Not Connected							

Connector Female 5 Pins (Center)

	•
Pin	Description
1	Not Connected
2	Line Bus A (Bus Out)
3	Not Connected
4	Line Bus B (Bus Out)
5	Not Connected

Connector 4 Pins (Right)

Pin	Description							
1	10 – 30 V DC							
2	Not Connected							
3	0 V							
4	Not Connected							



Example : MXM5DPC1B1213C10CH7200A

Contact the factory for special versions ex: overspeed switch, electronics, special flanges, connections ...

	MXM5	DP	C1	В	212	213	C	10C	H72	00A	
Aboslute Multiturn Encod	er 🗕					T		T			
MXM5											
Profibus											
DP											
Profibus Version ———											
C1											
Code											
B: Binary											
Number of Turns											
212: 4,096											
Resolution											
213: 8,192											
Clamp Flange											
C											
Shaft Diameter											
10C: 10mm											
Connection Cap											
H72: 3 x M12											
Encoder Version											
00A											

AGENCY APPROVALS & CERTIFICATIONS

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