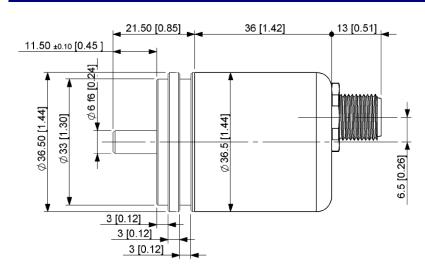
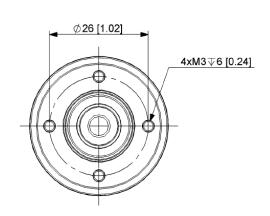
AHM4 is a Ø36mm singleturn encoder with CANopen interface:

- Compact and robust design.
- Solid shaft Ø 6 mm version.
- Precision sealed bearings.
- High temperature performance -40°C to 85°C.
- Hall effect technology.
- CANopen interface, binary code.
- 12 bits resolution = 4096 steps / turn (13 bits option available).
- Polarity inversions and surges protections.
- High integration SMD technology.



AHM4 M12 AXIAL DIMENSIONS





MECHANICAL CHARACTERISTICS

	Cover: steel		
Material	Body : aluminium		
	Blind shaft: stainless steel		
Maximum loads	Axial : 40 N		
Maximorniodas	Radial: 110 N		
Shaft inertia	≤ 30 g.cm²		
Torque	≤ 3 N.cm		
Max. speed (continuous)	12 000 rpm		

Shocks (EN 60068-2-27)	≤ 100 g (demi sinus, 6 ms)
Shocks (EN 60028-2-29)	≤ 10 g (demi-sinus, 16ms)
Vibrations (EN 60068-2-6)	≤ 10 g (10Hz 1 000Hz)
Weight (approx.)	150 g
Operating temperature	- 40 + 85°C
Storage temperature	- 40 + 85°C
Relative humidity	98 % without condensation
Protection grade	IP65



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MAGNETIC ENCODERS - CANOPEN ABSOLUTE SINGLE TURN - AHM4 RANGE

ELECTRICAL CHARACTERISTICS				
Interface	According to ISO 11898		Consumption	max 2,5W
Transmission	Max 1 MBauds		Accuracy	+/- 0,36°
Internal cycle time	<600 µs		EMC	EN 61000-6-4 EN 61000-6-2
Supply	10 - 30Vdc		Electrical life-time	> 10 ⁵ h

TRANSMISSION MODES				
POLLED mode	By a remote-transmission-request telegram the connected host calls for the current process value. The absolute rotary encoder reads the current position value, calculates eventually set-parameters and sends back the obtained process value by the same identifier			
CYCLIC mode	The absolute rotary encoder transmits cyclically - without being called by the host - the current process value. The cycle time can be programmed in milliseconds for values between 1 ms and 65536 ms			
SYNC mode	After receiving a sync telegram by the host, the absolute rotary encoder answers with the current process value. If more than one node number (encoder) shall answer after receiving a sync telegram, the answer telegrams of the nodes will be received by the host in order of their node numbers. The programming of an offset-time is not necessary. If a node should not answer after each sync telegram on the CAN network, the parameter sync counter can be programmed to skip a certain number of sync telegrams before answering again.			

PROGRAMMABLE PARAMETERS				
Operating Parameters	This parameter determines the counting direction, in which the output code increases or decreases. As an important operating parameter the code sequence (complement) can be programmed			
Resolution per t	turn Value between 1 and 4096 can be programmed			
Preset Value	The preset value is the desired position value, which should be reached at a certain physical position of the axis			
Limit Switch, Min. and Max	Two position values can be programmed as limit switches. By reaching these values one bit of the 32 bit process value is set to high level			

CONFIGURATION

The standard configuration is: node number = 32 and Baurate = 125kBaud. These configurations can be modified with SDO frames. The Baudrate can be modified from 20kBaud to 1MBaud. The node number can de programmed between 0 and 89.

CANopen CONNECTION					
GND	+Ub = 10-30Vdc	CAN-High	CAN-Gnd	CAN-Low	
3	2	4	1	5	

ORDERING REFERENCE (specific manufacture on demand. ex: flange / specific connection)					
AHM4	CA00	В	0012	R060	PAM
Absolute singleturn encoder	CANopen	Binary	12 bits per turn	6mm Solid shaft	M12 axial

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